



WHITE ELEPHANT GMBH

# SkyTrack

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## Reference Manual

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<b>Version:</b>	<b>Modified:</b>	
<b>1.0</b>	5-Oct-17	Original Issue
<b>1.1</b>	21-Dec-17	LX 200 protocol support
<b>1.2</b>	25-Oct-18	New SkyTracker hardware
<b>1.3</b>	8-Jan-19	Support different steps/rev per axis
<b>1.4</b>	31-May-19	Allow synch on targets
<b>1.5</b>	20-Jan-21	Equatorial mounts only

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## 1 Introduction

SkyTrack is a PC program that is able to control the movement of a telescope to find and follow stars, planets, deep sky objects, small solar system bodies (SSSB) such as comets or near earth objects such as satellites.

The program supports telescopes that have simple stepper motors (without decoders) with Equatorial mountings.

The telescope can be controlled using the program's graphical user interface (GUI), a numeric keypad or via Stellarium. In the latter case the program sends feedback to Stellarium so that it can keep its display up to date. The use of Stellarium is not a requirement.

Other features that are often missing from contemporary products include:

- Favorites: a list of frequently observed objects.
- Horizon: For fixed telescopes and those at their "home" location, the actual horizon can be defined. The actual horizon differs from the true horizon when buildings obscure the true horizon. This feature allows the program to improve the accuracy of its filtering of visible objects.
- Only list objects that can currently be seen or, in the case of NEOs, are soon to be seen.
- Catalogs: Objects can be named according to a variety of catalogs. The same astronomical object is called different things according to the catalog used.
- On Earth Objects: For demonstration purposes, when the weather is overcast, it is sometimes useful to be able to position the telescope onto a nearby terrestrial object (e.g. a road sign). In this case the rotation of the earth must be ignored.
- Park position: For fixed telescopes or those at their "home" location, it is useful to park the telescope to a known position before powering off. This saves the need to realign the telescope next time it is used.
- Normal and Expert modes: Useful to prevent shared or public telescopes from being accidentally misconfigured.

## 2 Getting Started

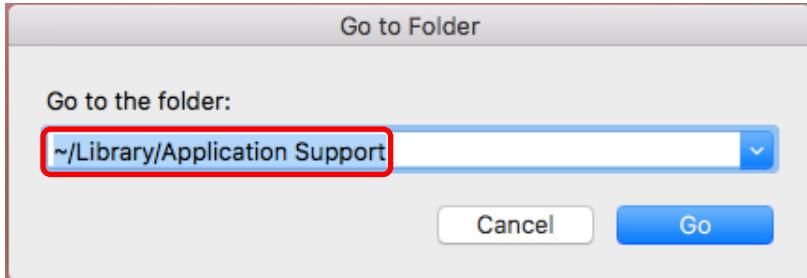
The easiest way to get SkyTrack running is to follow the instructions of the SkyTrack User Manual.

### 3 Configure SkyTrack

#### 3.1 Locate the configuration data directory

##### 3.1.1 OSX

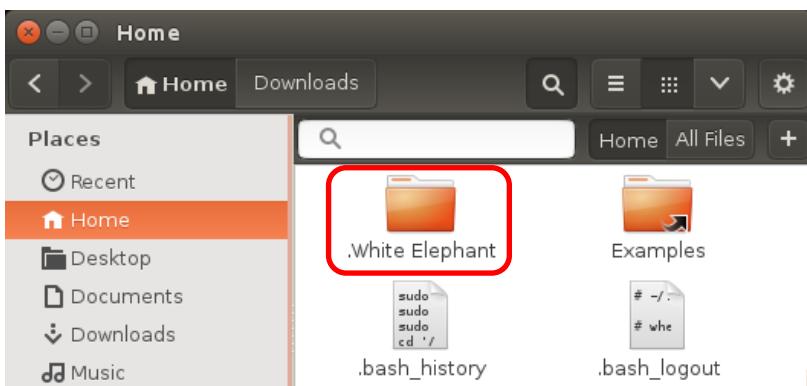
First open the application data directory by starting the **Finder's Go to Folder...** and then entering: **~/Library/Application Support**



Then browse to the SkyTrack data subdirectory: **White Elephant/SkyTrack**

##### 3.1.2 Linux

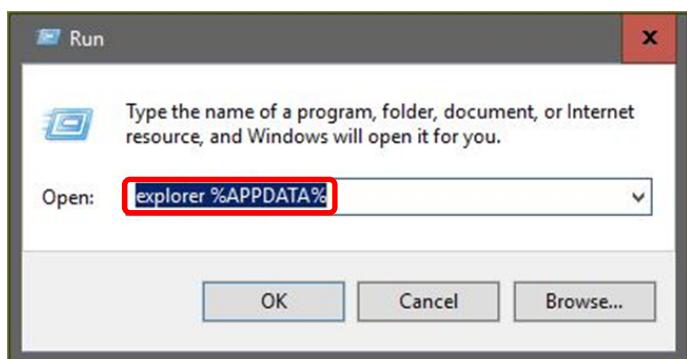
First open **Home** and make the hidden directories visible by entering: **Ctrl-h**



Then browse to the SkyTrack data subdirectory: **.White Elephant** and then **SkyTrack**

##### 3.1.3 Windows 10

First open the application data directory by executing: **explorer %APPDATA%**



Then browse to the SkyTrack data subdirectory: **White Elephant\SkyTrack**

## 3.2 Contents of SkyTrack data directory

Name	Date modified	Type	Size
Data	21/11/2020 20:36	File folder	
Neo	29/11/2020 21:34	File folder	
Sky Line	16/10/2020 17:56	File folder	
2020_SO.sssb	26/11/2020 19:11	SSSB File	59 KB
Favorites.txt	26/11/2020 19:41	Text Document	2 KB
Log.ini	03/11/2020 18:55	Configuration sett...	1 KB
SkyTrack.ini	01/12/2020 14:31	Configuration sett...	1 KB

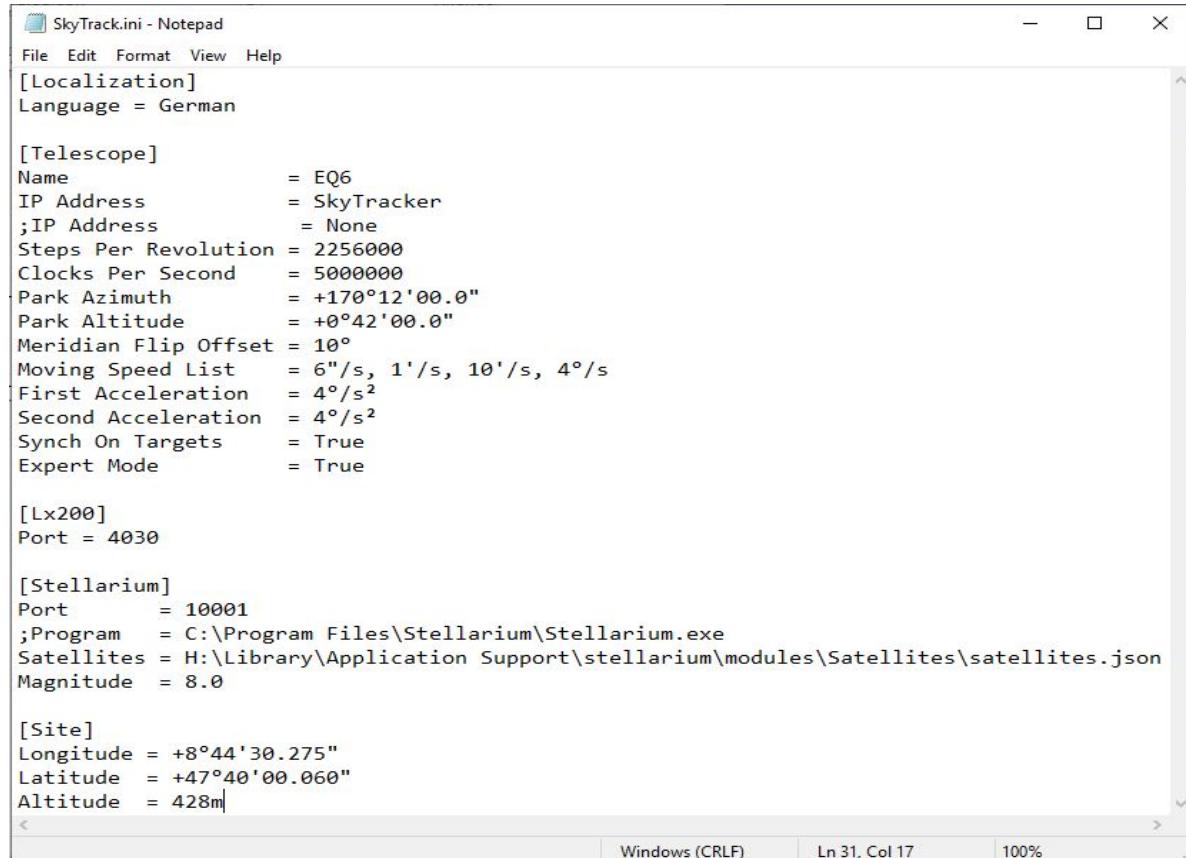
This directory contains the following configuration data:

- SkyTrack.ini → program configuration data
- Favorites.txt → list of the favorite sky objects
- Log.ini → configuration of program logging
- Sky Line → sky line definition data
- Neo → near earth object information
- Data → binary program data
- 2020\_SO.sssb → ephemeris for a small solar system body

### 3.2.1 Program configuration data (SkyTrack.ini)

The file SkyTrack.ini contains information on how to control the telescope. It is automatically generated when SkyTrack is first started. If Stellarium is already installed and configured, its configuration is taken to initialize the language and site information.

The content of the configuration file is split into the sections Localization, Telescope, Stellarium and Site.



```
SkyTrack.ini - Notepad
File Edit Format View Help
[Localization]
Language = German

[Telescope]
Name = EQ6
IP Address = SkyTracker
;IP Address = None
Steps Per Revolution = 2256000
Clocks Per Second = 5000000
Park Azimuth = +170°12'00.0"
Park Altitude = +0°42'00.0"
Meridian Flip Offset = 10°
Moving Speed List = 6"/s, 1'/s, 10'/s, 4°/s
First Acceleration = 4°/s2
Second Acceleration = 4°/s2
Synch On Targets = True
Expert Mode = True

[Lx200]
Port = 4030

[Stellarium]
Port = 10001
;Program = C:\Program Files\Stellarium\Stellarium.exe
Satellites = H:\Library\Application Support\stellarium\modules\Satellites\satellites.json
Magnitude = 8.0

[Site]
Longitude = +8°44'30.275"
Latitude = +47°40'00.060"
Altitude = 428m
```

The Localization section contains:

- **Language** = <language>  
The language is English, French, German, Greek, Italian or Spanish.

The Telescope section contains the following properties:

- **Name** = <name>  
The Telescope's <name> to be shown in the SkyTrack windows title bar.
- **IP Address** = <address or name>  
If the name is "SkyTracker" for Windows (or "SkyTracker.local" for Linux and OSX) then SkyTracker hardware must be connected via Ethernet. If the name is "None" then the telescope is simulated.
- **Steps Per Revolution** = <number>  
Defines the number of micro steps used to turn a telescope axis by 360°.  
The SkyTracker hardware stepper controller uses 16 micro steps per step.  
  
If the gearing is different per axis the two values must be individually defined.  
**First Steps Per Revolution** = <number>  
**Second Steps Per Revolution** = <number>
- **Clocks Per Second** = <number>  
Defines the time resolution of the actual hardware. For the SkyTracker hardware a value of 5,000,000 is used.
- **Park Azimuth** = <angle>  
**Park Altitude** = <angle>  
Park azimuth and altitude define the telescopes park position.
- **Moving Speed List** = <speed>, <speed>, <speed>, <speed> ...  
An ascending list of speeds is used to manually control the telescope via the arrow keys. The + and - keys change from one value to the next or previous. The last value of the list is the maximum speed for all movements except when adjusting (movements whilst tracking an object).
- **First Acceleration** = <acceleration>  
Defines the maximum acceleration for right ascension axis.
- **Second Acceleration** = <acceleration>  
Defines the maximum acceleration for the declination axis.
- **Meridian Flip Offset** = <angle>  
Specifies for right ascension offset value for a meridian flip.
- **Synch On Targets** = <boolean>  
Defines if synch on targets is allowed (**True** or **False**).
- **Expert Mode** = <boolean>  
Sets the expert mode to **True** or **False**. (See Chapter 4)

The Lx200 section contains:

- **Port** = <number>

Defines the port number for the Lx200 protocol server. This enables a smart phone or tablet computer to control the telescope.

Examples:

**SkySafari 5 Pro** (Telescope Setup: Scope Type – Meade LX-200 Classic)

The Stellarium section contains:

- **Port** = <number>

Defines the port number used by the Stellarium telescope control.

- **Program** = <path and filename of the Stellarium application (stellarium.exe)>  
[optional] If defined Stellarium starts automatically when SkyTrack is started.

- **Satellites** = <path and filename of the satellites data file (satellites.json)>  
[optional] If not defined no satellites from Stellarium are added to the NEO list.

- **Magnitude** = <number>

[optional] Defines the magnitude limit for Satellites. If not defined all visible satellites are added to the NEO list.

The Site section contains:

- **Longitude** = <angle>

**Latitude** = <angle>

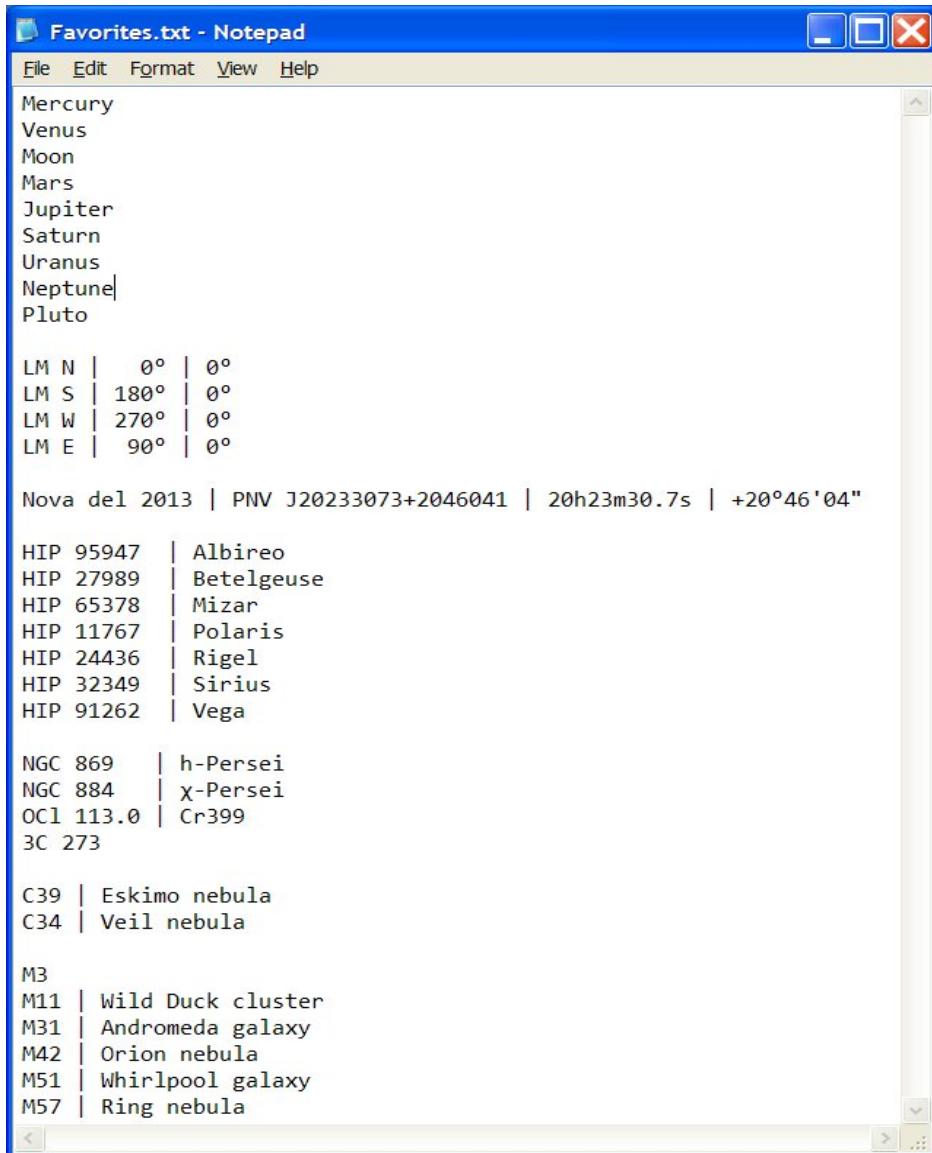
**Altitude** = <angle>

Telescope location information.

### 3.2.2 Favorites list of Sky Objects (Favorites.txt)

The file Favorites.txt is automatically generated when SkyTrack is first started. In this file, one object per line of text can be defined. Empty lines are allowed.

For example:



Favorites.txt - Notepad

File Edit Format View Help

Mercury  
Venus  
Moon  
Mars  
Jupiter  
Saturn  
Uranus  
Neptune|  
Pluto

LM N | 0° | 0°  
LM S | 180° | 0°  
LM W | 270° | 0°  
LM E | 90° | 0°

Nova del 2013 | PNV J20233073+2046041 | 20h23m30.7s | +20°46'04"

HIP 95947 | Albireo  
HIP 27989 | Betelgeuse  
HIP 65378 | Mizar  
HIP 11767 | Polaris  
HIP 24436 | Rigel  
HIP 32349 | Sirius  
HIP 91262 | Vega

NGC 869 | h-Persei  
NGC 884 | x-Persei  
OCl 113.0 | Cr399  
3C 273

C39 | Eskimo nebula  
C34 | Veil nebula

M3  
M11 | Wild Duck cluster  
M31 | Andromeda galaxy  
M42 | Orion nebula  
M51 | Whirlpool galaxy  
M57 | Ring nebula

### 3.2.3 Solar Objects

For solar objects, any of the following names, in any of the supported languages, are allowed:

- Sun  
**Warning: if no solar filter is in use, the sun must not be added to the list.**
- Moon
- Mercury
- Venus
- Mars
- Jupiter
- Saturn
- Neptune
- Pluto

### 3.2.4 Small Solar System Bodies (SSSB)

A file with the extension **.sssb**, placed in the folder where the file Favorites.txt is located, defines an SSSB. The name can then be added to the favorites list.

Examples:

**C2015-V2(Johnson)**

### 3.2.5 Objects from Catalogs

The following syntax defines an object:

```
<object_id>
    or
<object_id> | <name>
```

For Caldwell and Messier objects the name is appended to the object id. For the other objects the name replaces the object id.

Examples:

**HIP 32349** | Sirius      (**Sirius** in favorite list)  
**M57** | Ring Nebula      (**M57 Ring Nebula** in favorite list)

Objects can be defined from any of the following integrated catalogs.

- Caldwell
- HIP
- HR
- Messier
- NEO
- NGC
- OCL
- Quasars

### 3.2.6 Sky Objects

The following syntax defines a sky object:

```
<name> | <description> | <right ascension> | <declination>
```

Example:

**Nova Del 2013** | PNV J20233073+2046041 | 2h23m30.7s | +20°46'04"

### 3.2.7 On Earth Objects

The id "LM" (Land Marks) starts the definition for stationary objects.

```
LM <name> | <azimuth> | <altitude>
```

Examples:

**LM Road Sign** | 259°43' | 2°38'  
**LM West** | 270° | 0°

### 3.3 Small Solar System Bodies

A small solar system body (SSSB) is an object in the solar system that is neither a planet, nor a dwarf planet, nor a satellite. For example: comets are small solar system bodies.

To track an SSSB, a table of its future positions - so called ephemerides – has to be downloaded.

#### 3.3.1 Download Ephemerides

The following Web-Interface allows the downloading of ephemerides:

<https://ssd.jpl.nasa.gov/horizons.cgi>

This tool provides a web-based *limited* interface to JPL's HORIZONS system which can be used to generate ephemerides for solar-system bodies. Full access to HORIZONS features is available via the primary telnet interface. HORIZONS system news shows recent changes and improvements. A web-interface tutorial is available to assist new users.

**Current Settings**

Ephemeris Type [change] : **OBSERVER**  
Target Body [change] : **Mars** [499]  
Observer Location [change] : **Paris France** ( 2°19'59.9"E, 48°51'00.0"N )  
Time Span [change] : Start=2017-07-01, Stop=2017-07-31, Step=1 d  
Table Settings [change] : *defaults*  
Display/Output [change] : *default* (formatted HTML)

Generate Ephemeris

#### 3.3.1.1 Change Target Body

**Target Body**

Lookup the specified body:  
C/2015 V2 optionally limit to all bodies (no limit)

#### 3.3.1.2 Change Observer Location

**Specify Observer Location:**

You can specify a topocentric observer location by choosing from a list of major world cities, by choosing from a list of world-wide observatories, or by giving the latitude, longitude, and altitude. You can also specify non-topocentric Horizons-specific location codes such as the sun or another planet.

Please select from the following list:

- lookup a named location
- choose from a list of locations
- **specify latitude, longitude, and altitude**

#### Specify Observer Coordinates

Longitude and Latitude can be entered as either "degrees minutes seconds" or decimal degrees. In either case, they should always be positive and use the appropriate East/West and North/South selections. If entering "degrees minutes seconds" use spaces or commas between elements. If Altitude is unknown, zero can be used for optical sites without much loss of accuracy.

Longitude: 8.60986388888888 degrees  East  West  
Latitude: 47.70550277777777 degrees  North  South  
Altitude: 0.54 kilometers  above the reference ellipsoid {WGS-84, or approx. sea level for Earth}  
Body ID: 399 Horizons body ID of the central body: e.g. '399' for Earth, '499' for Mars

#### 3.3.1.3 Change Time Span

##### Time Span

switch to discrete-times form

Preset:

Available time span for currently selected target body:  
1599-Dec-12 to 2500-Dec-30 TT.

Start Time: 2017-07-01

Times may be specified as calendar dates and optionally times  
(e.g. "YYYY{BC|AD}-MM-DD {hh:mm} {UT|TT}"', or Julian dates (e.g. "{JD }  
DDDDDD.DDDD") where items in curly braces {} are optional. For years  
earlier than 1000, be sure to append 'AD' (or 'BC' as appropriate).  
Unless otherwise specified, UT is assumed for OBSERVER  
tables.

Stop Time: 2017-08-30

Step Size: 1 hours

See the [HORIZONS documentation](#) for accepted formats and  
advanced capabilities. Allowable time-spans for all bodies are  
available on a [separate page](#).

#### 3.3.1.4 Change Table Settings

1.  Astrometric RA & DEC

16.  Sub-Sun position angle & distance

\* 31.  Observer ecliptic lon. & lat.

\* 2.  Apparent RA & DEC

17.  North Pole position angle & distance

32.  North pole RA & DEC

3.  Rates; RA & DEC

18.  Heliocentric ecliptic lon. & lat.

33.  Galactic longitude & latitude

\* 4.  Apparent AZ & EL

19.  Heliocentric range & range-rate

34.  Local apparent SOLAR time

5.  Rates; AZ & EL

20.  Observer range & range-rate

35.  Earth->obs. site light-time

6.  Satellite X & Y, pos. angle

21.  One-way (down-leg) light-time

> 36.  RA & DEC uncertainty

7.  Local apparent sidereal time

22.  Speed wrt Sun & observer

> 37.  Plane-of-sky error ellipse

8.  Airmass & extinction

23.  Sun-Observer-Target ELONG angle

> 38.  POS uncertainty (RSS)

9.  Visual mag. & Surface Bright

24.  Sun-Target-Observer ~PHASE angle

> 39.  Range & range-rate 3-sigmas

10.  Illuminated fraction

25.  Target-Observer-Moon angle/ Illum%

> 40.  Doppler & delay 3-sigmas

11.  Defect of illumination

26.  Observer-Primary-Target angle

41.  True anomaly angle

12.  Satellite angular separ/vis.

27.  Sun-Target radial & -vel pos. angle

42.  Local apparent hour angle

13.  Target angular diameter

28.  Orbit plane angle

43.  PHASE angle & bisector

14.  Observer sub-lon & sub-lat

29.  Constellation ID

15.  Sun sub-longitude & sub-latitude

30.  Delta-T (TDB - UT)

##### Notes:

- \* affected by optional atmospheric refraction setting (below)
- > statistical value that uses orbit covariance if available

Observer quantities are described in the [HORIZONS documentation](#).

**Optional observer-table settings:**

date/time format :	both	-- display date/time in year-month-day and/or Julian-day format
time digits :	minutes (HH:MM)	-- controls output precision of time
angle format :	decimal degrees	-- select RA/Dec output format
output units :	km & km/s	-- units for most output quantities
range units :	astronomical units	-- units for range-type quantities
refraction model :	airless model (no refraction)	-- select atmospheric refraction model
airmass cut-off :		-- suppress output when airmass is greater than limit [1 to 38]
elevation cutoff :	0	(deg) -- suppress output when object elevation is less than limit [-90 to 90]
solar elong. cut-off :		(deg) -- suppress output when solar elongation is outside (min,max) range [0 to 180, min to 180]
hour angle cutoff :		(h) -- suppress output when the local hour angle (LHA) exceeds value [0 to 12]
angular rate cutoff :		(arcsec/h) -- suppress output when the RA/Dec angular rate exceeds this value [0 to 100000]
suppress range-rate :	<input type="checkbox"/>	-- suppress range-rate for range/range-rate output
skip daylight :	<input type="checkbox"/>	-- suppress output during daylight
extra precision :	<input type="checkbox"/>	-- output addition digits for RA/Dec quantities
RTS flag :	disable	<input checked="" type="checkbox"/> -- output data only at target rise/transit/set (RTS)
reference system :	ICRF/J2000.0	<input checked="" type="checkbox"/> -- reference frame for geometric and astrometric quantities
CSV format :	<input checked="" type="checkbox"/>	-- output data in Comma-Separated-Values (CSV) format
object page :	<input checked="" type="checkbox"/>	-- include object information/data page on output

**Buttons:**

**Use Settings Above**   **Default Optional Settings**   **Cancel**

### 3.3.1.5 Change Display/Output

<input type="radio"/> HTML (default)	Ephemeris results will be shown in a normal formatted web page.
<input type="radio"/> plain text	Ephemeris results will be displayed as plain text (ASCII).
<input checked="" type="radio"/> download/save	Ephemeris results will be saved to a local file (this assumes your browser supports file downloads)

**Buttons:**

**Use Selection Above**   **Cancel**

### 3.3.1.6 Generate Ephemerides

**Current Settings**

Ephemeris Type [change] : OBSERVER  
 Target Body [change] : Comet C/2015 V2 (Johnson)  
 Observer Location [change] : user defined ( 8°36'35.5"E, 47°42'19.8"N, 0.54 km )  
 Time Span [change] : Start=2017-07-11, Stop=2017-09-09, Step=1 h  
 Table Settings [change] : QUANTITIES=1; date/time format=BOTH; angle format=DEG; elevation cutoff=0;  
 CSV format=YES  
 Display/Output [change] : download/save (plain text file)

**Buttons:**

**Generate Ephemeris**

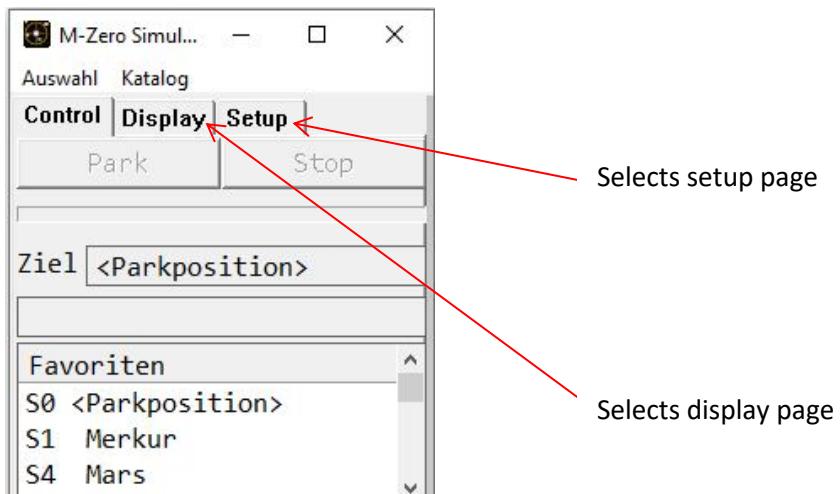
Do you want to open or save **horizons\_results.txt** from [ssd.jpl.nasa.gov](http://ssd.jpl.nasa.gov)?   **Open**   **Save**   **Cancel**

The new file **horizons\_result.txt** can now be renamed to **C2015-V2(Johnson).sss** and then placed in the same folder where the file **Favorites.txt** is located. Then the name **C2015-V2(Johnson)** can be added to the favorites list.

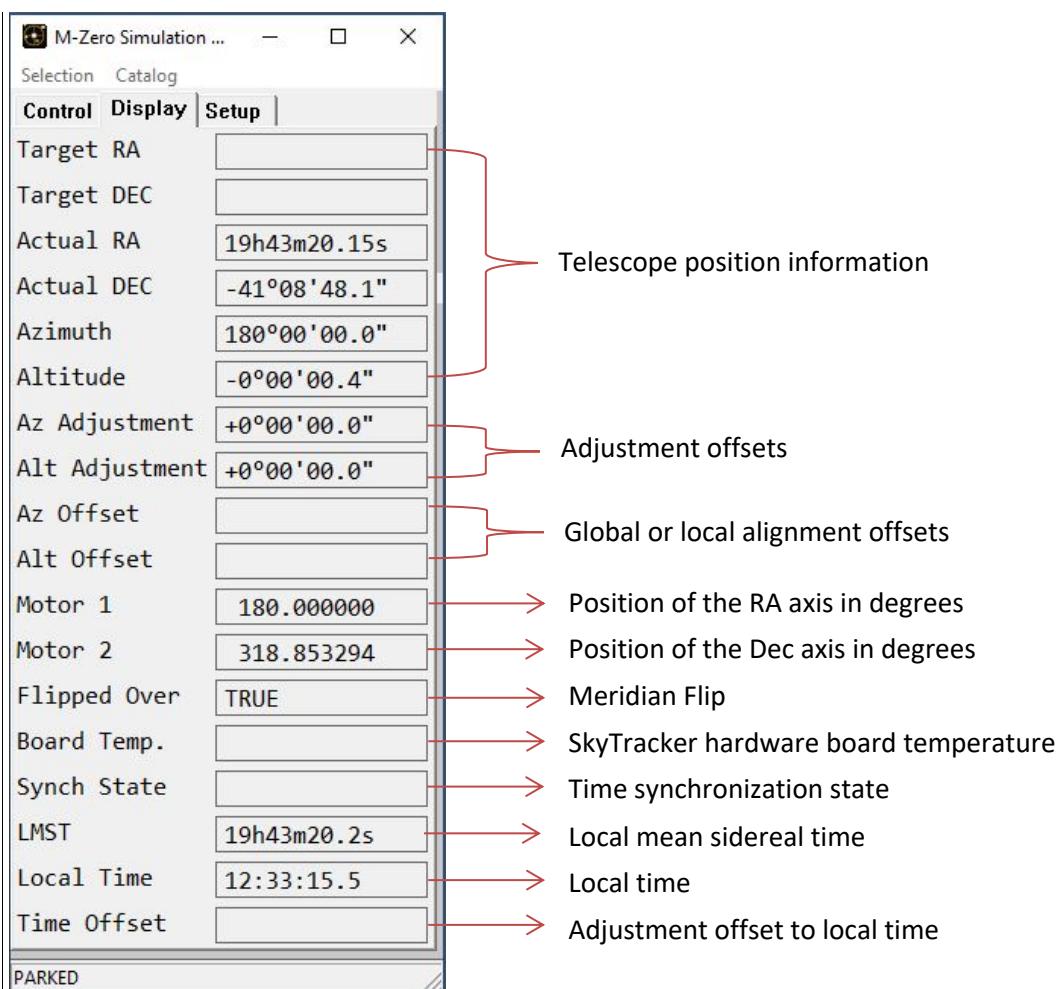
## 4 Telescope Setup

To enable a telescope setup the mode has to be changed to expert mode. This can be achieved by setting the expert mode to **True** in the SkyTrack.ini file.

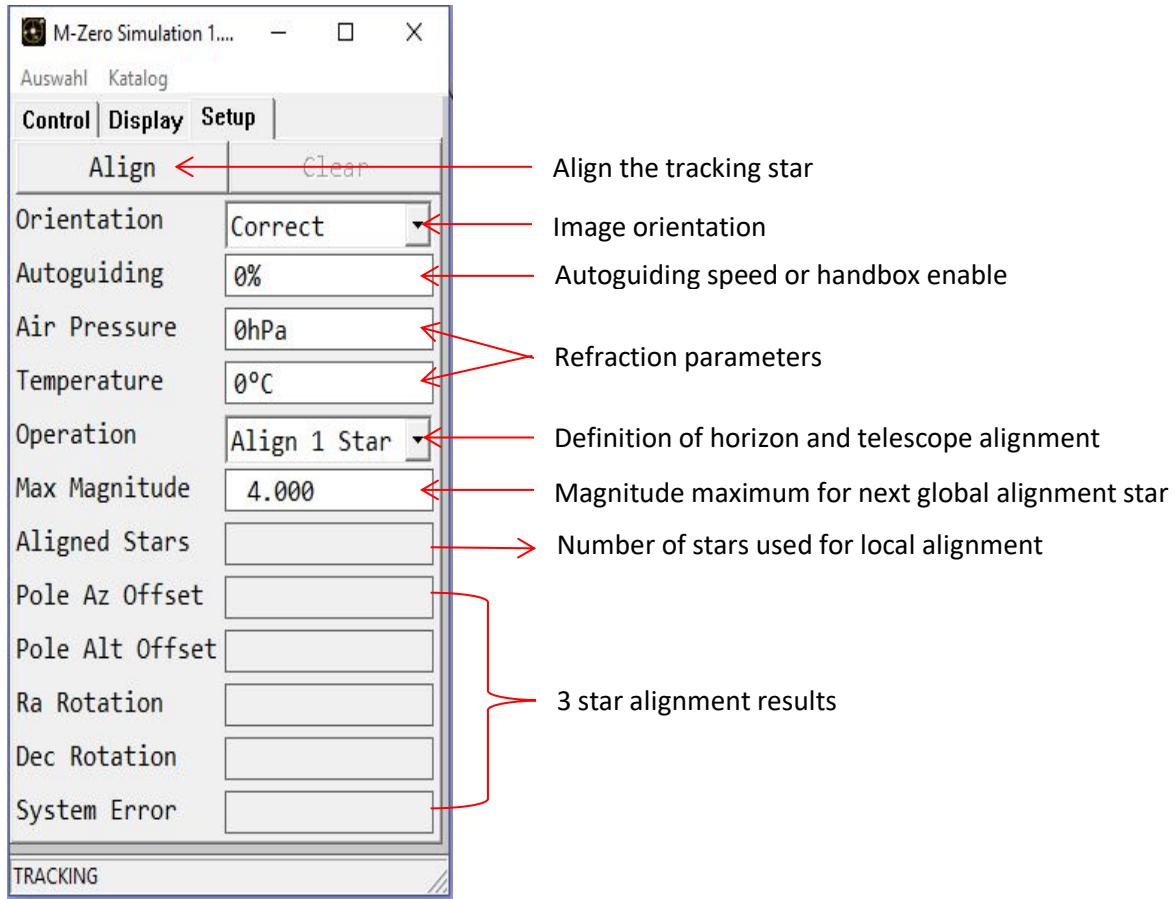
After the next start of SkyTrack the following should be visible:



### 4.1 Display Page



## 4.2 Setup Page



### 4.2.1 Image Orientation

Whilst tracking, the meaning of the arrow keys to adjust a sky object can be changed.  
The pull-down menu allows the selection of one of the following image orientations:

- **Correct**
- **Upside Down** Up - Down keys swapped.
- **Backwards** Left - Right keys swapped.
- **Rotated** Up - Down and Left - Right keys swapped.

### 4.2.2 Autoguiding Speed

The speed for autoguiding is defined in arc seconds per second. A typical value would be **8"/s**.  
A value of **0"/s** allows the use of a handbox instead of an autoguiding camera.

### 4.2.3 Refraction Parameters

Two parameters are used to correct the refraction.

- Air Pressure in hecto Pascal
- Temperature in degrees Celsius

A value of zero for the air pressure switches off the refraction corrections.

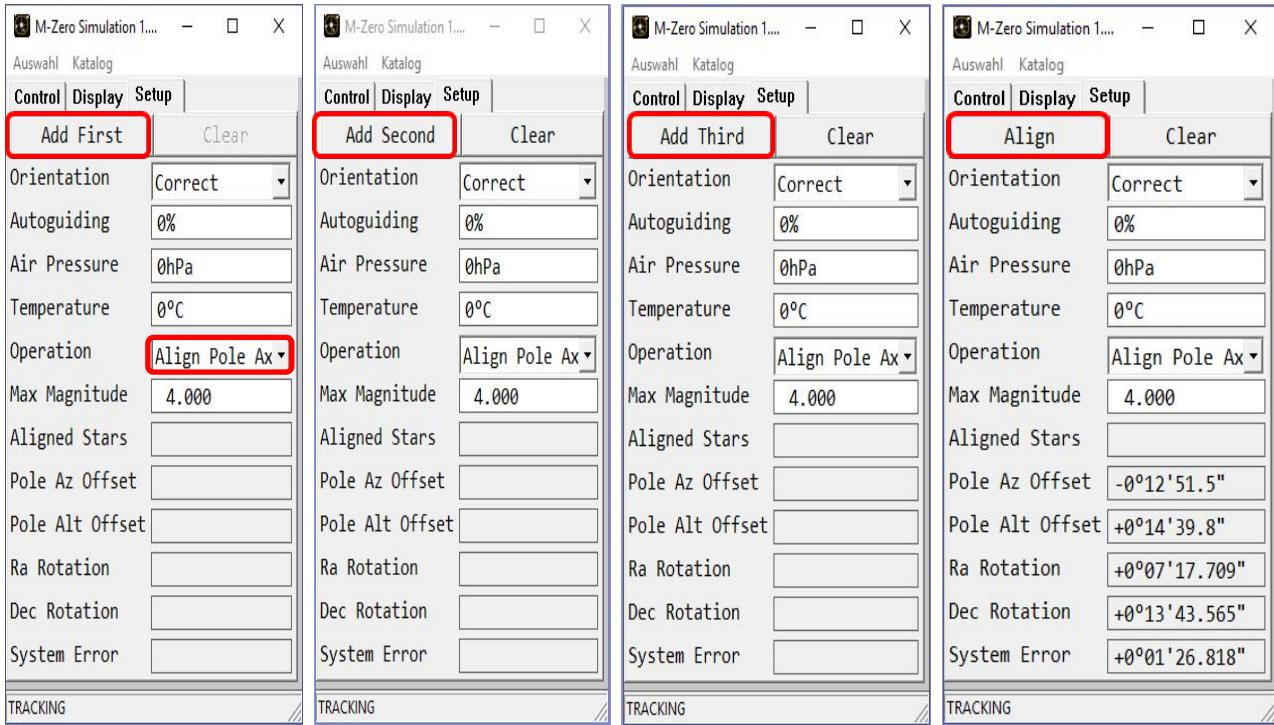
### 4.2.4 Setup Operation

One of the following operations can be selected (see corresponding chapter for more information).

- **Align 1 Star** to Synch to the tracking object (clears the adjustment offsets).
- **Align Pole Axis** to adjust the pole axis (only for equatorial mounts).
- **Align Global** alignment using many stars to generate a global correction matrix.
- **Align Local** local alignment (if autoguiding is not possible).
- **Set Sky Line** to define the actual horizon.

## 4.3 Pole Axis Alignment

To align the pole axis of an equatorial mount three stars have to be aligned. The stars should not be close to the pole or zenith and the altitude should be greater than 30 degrees. After aligning the third star, the telescope is positioned so that mechanically aligning it back to the third star the pole axis will be aligned. The Synch button allows synchronizing the RA and Dec axis. The System Error depends on the quality of the telescope and how precise the aligning was done. If the error is too big the Clear button can be used to allow a new alignment procedure



## 4.4 Local Alignment

If autoguiding is not possible, local alignment can be used to position the telescope more precisely in a local area. At least five stars have to be aligned. After the telescope is stopped the Apply button completes the operation.



## 4.5 Global Alignment

The global alignment operation allows the alignment of typically around 50 stars to build a global correction matrix. The alignment information is added to a file called **New\_Data.txt** in the alignment folder in the SkyTrack application data area. To keep the file it can be renamed.

After the Align Global operation is selected the next tracked star enables the adding of alignment data. The next star is positioned automatically according to the first star's altitude and the chosen maximum magnitude. If there are no more stars to add in the current altitude band, the operation can be restarted to add data at a different altitude. The Next button allows going to the next star without adding the data of the actual star.

The screenshot shows the 'Control' tab of the M-Zero Simulation 1... software. The 'Add' button is highlighted with a red box. The 'Operation' dropdown menu is set to 'Align Global'. To the right, a file explorer window shows the file path: << AppData > Roaming > White Elephant > SkyTrack > Alignment. It lists two files: 'Data.txt' and 'New\_Data.txt', both modified on 31/05/2019 18:26. The 'New\_Data.txt' file is also highlighted with a red box.

To use the Information for a global correction matrix the file has to be renamed to **Data.txt** and SkyTrack has to be restarted.

## 4.6 Set Sky Line

To define the actual horizon the telescope has to be directed to landmarks at the horizon and then by pushing the add button added to the database. The database is located in the sky line folder of the SkyTrack application data area.

The screenshot shows the 'Control' tab of the M-Zero Simulation 1... software. The 'Add' button is highlighted with a red box. The 'Operation' dropdown menu is set to 'Set Sky Line'. To the right, a file explorer window shows the file path: << AppData > Roaming > White Elephant > SkyTrack > Sky Line. It lists three CSV files: 'Home.csv', 'Horizon.csv', and 'New\_Horizon.csv'. The 'New\_Horizon.csv' file is highlighted with a red box.

The **New\_Horizon.csv** file has to be renamed to **Horizon.csv** and then SkyTrack has to be restarted.

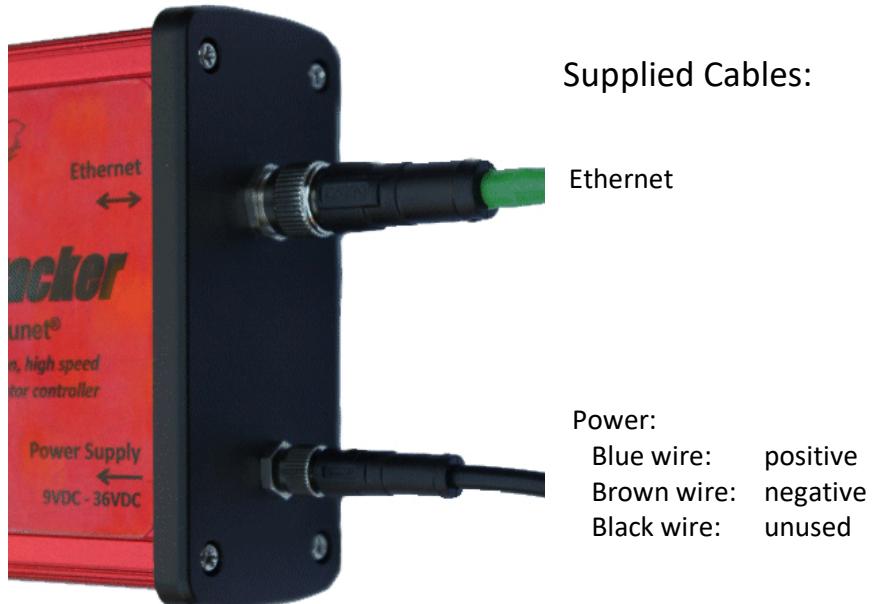
## 5 Hardware

### 5.1 Stepper Controller

The SkyTracker controller is connected via Ethernet to a PC running the SkyTrack program. A handbox or an autoguider can be connected to the guider input.



#### 5.1.1 Power and Ethernet Connections



### 5.1.2 Motor and Guider Connections

#### Supplied Cables:

##### Motors:

- White and Brown wires: Coil A
- Black and Blue wires: Coil B



##### Guider:

- Brown wire: ST4 Yellow
- Green wire: ST4 Blue
- Pink wire: ST4 Green
- Blue wire: ST4 Red
- Red wire: ST4 Black

##### Sync:

- Yellow wire: Pulse
- Red wire: GND

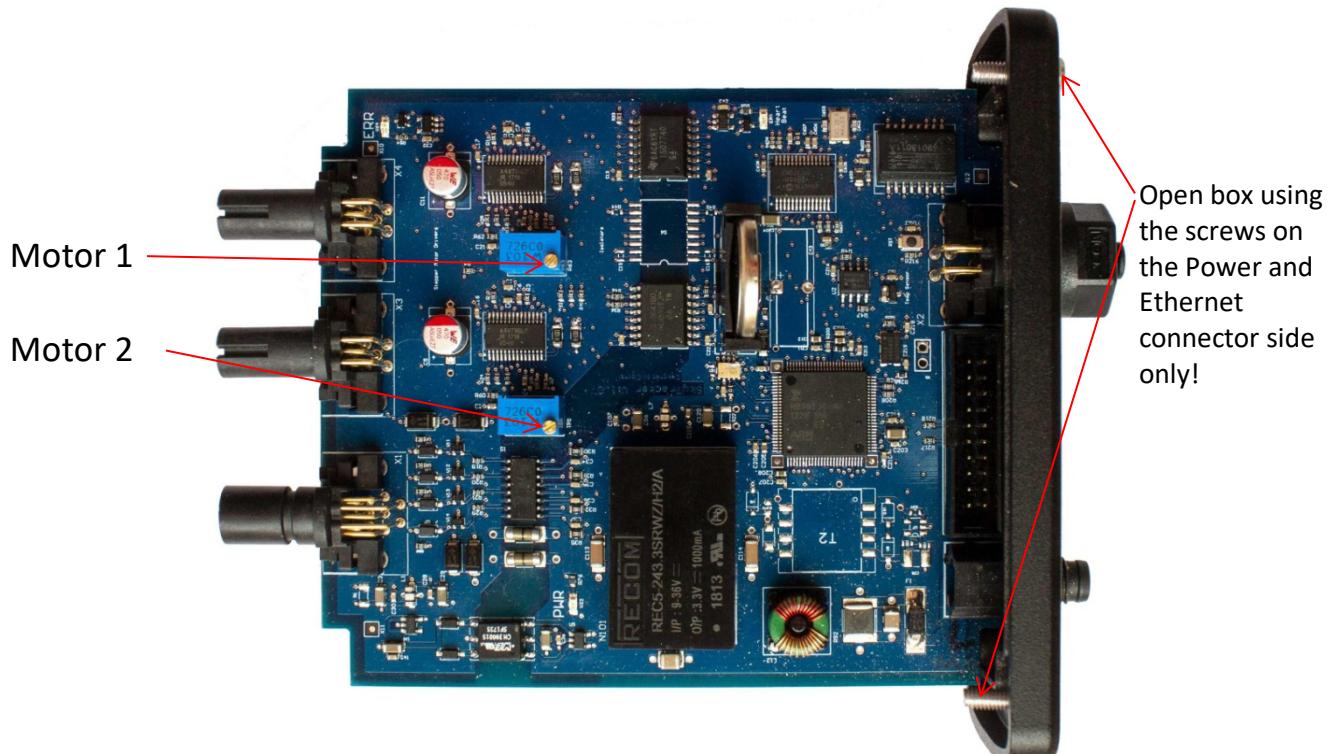
To change the direction of the motor rotation either the white and brown or the black and blue wires must be swapped. The ST4 wiring for the RJ12 connector is documented in chapter 5.2.2.

The sync pulse can be used to synchronize the internal clock to an external time reference - further details on request.

The white and grey wires are reserved for future development. These must be left disconnected.

### 5.1.3 Stepper Controller Board

Two potentiometers on the controller board are used to adjust the current of the stepper motors.

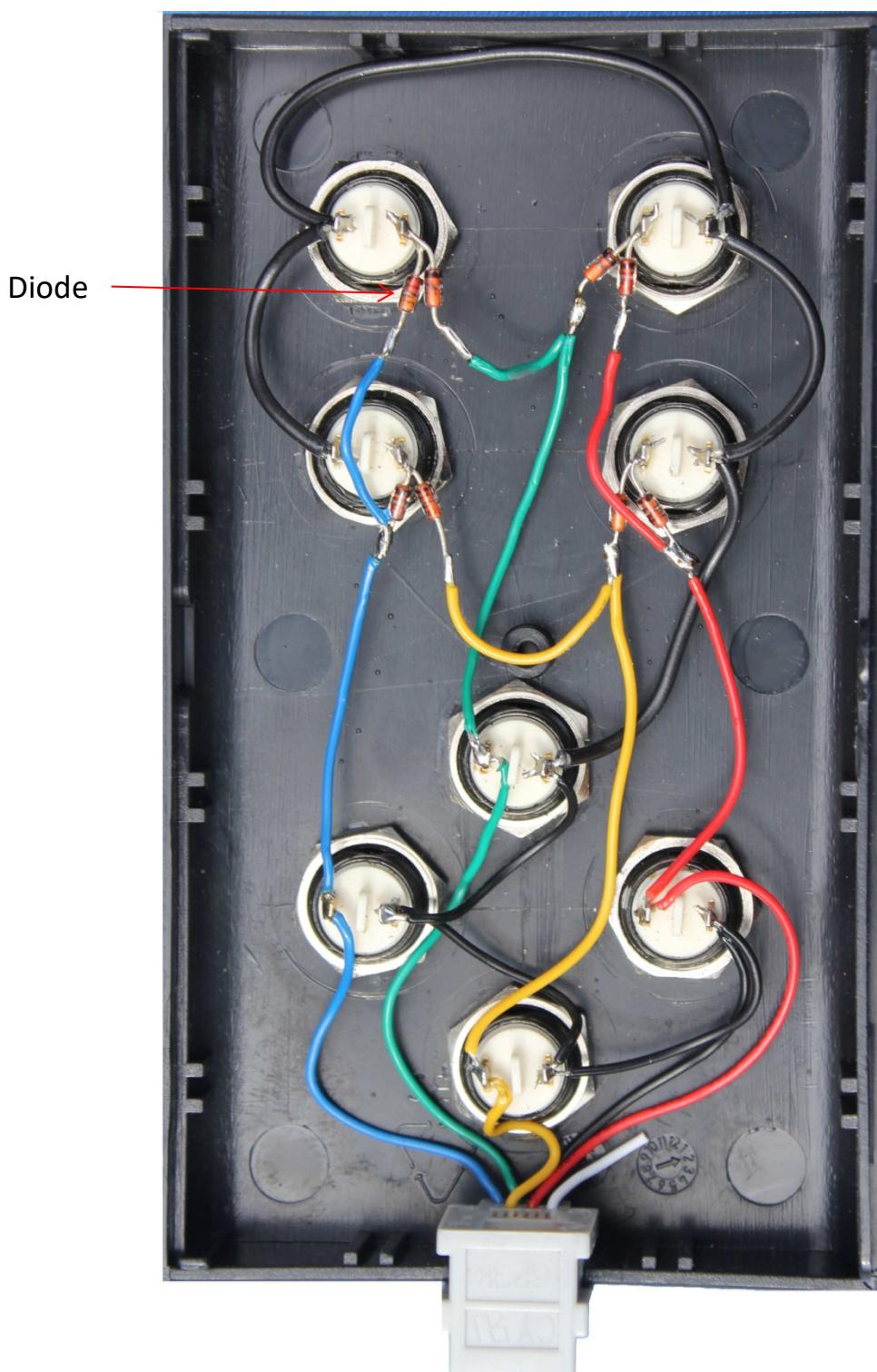


## 5.2 Handbox

The following pictures show a possible handbox implementation.

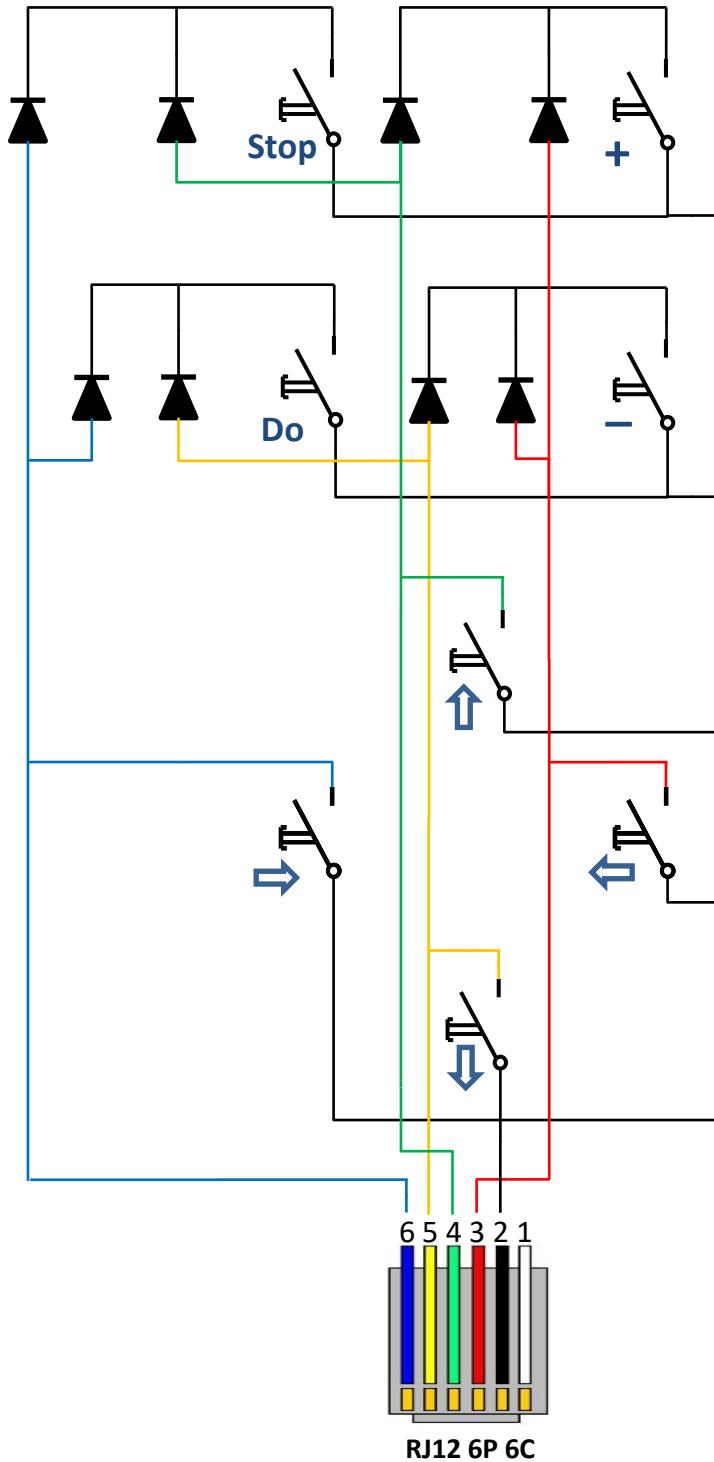


### 5.2.1 Handbox Inside



### 5.2.2 Handbox Schematics

The handbox is shown from the back (left and right is swapped).  
For the diodes the type 1N4148 could be used.



RJ12 wiring for autoguiding (ST4) with supplied Guider Cable:

- 1 – Not connected
- 2 – Red wire
- 3 – Blue wire
- 4 – Pink wire
- 5 – Brown wire
- 6 – Green wire

## 6 Legacy Hardware

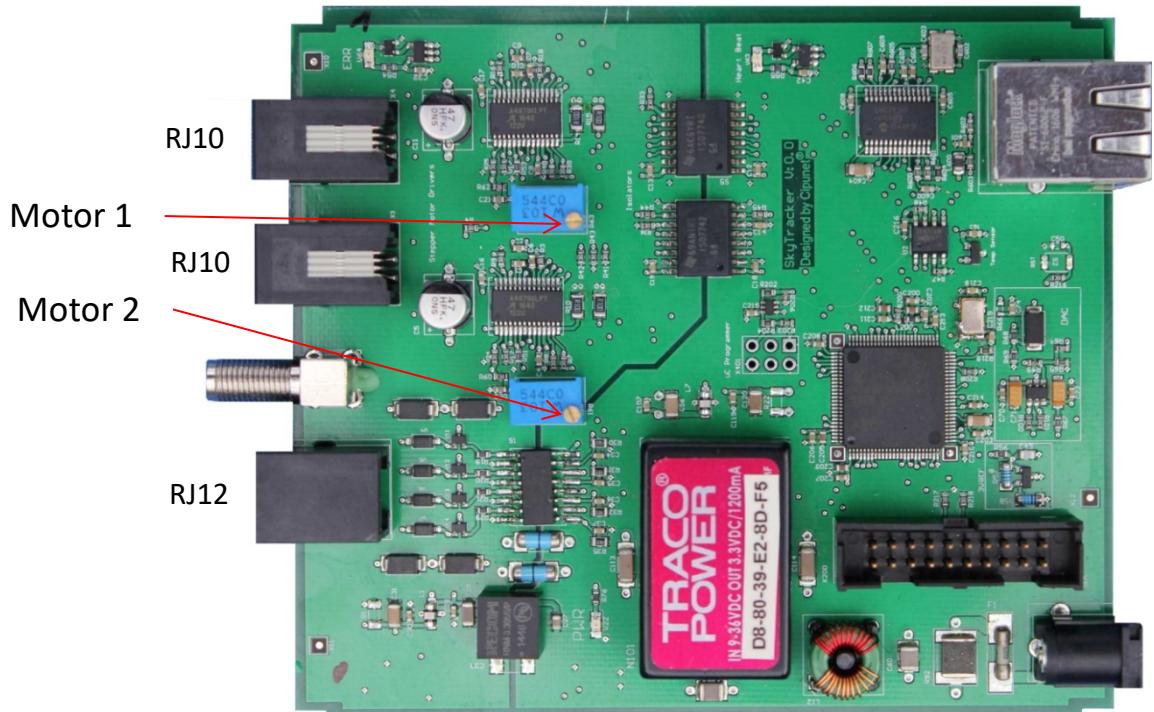
### 6.1 Stepper Controller

The SkyTracker controller is connected via Ethernet to a PC running the SkyTrack program. A handbox or an autoguider (ST4) can be connected to the guider input.



#### 6.1.1 Stepper Controller Board

Two potentiometers on the controller board are used to adjust the current of the stepper motors.



The stepper motors coil A (B) have to be connected to pins 1 and 2 (3 and 4) of the RJ10 connectors. To change the direction of rotation either the connections 1 and 2 or else 3 and 4 must be swapped.